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ANTIPODALLY SYMMETRIC DISTRIBUTIONS FOR ORIENTATION STATISTICS.

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Antipodally symmetric distributions for orientation statistics

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SUMMARY

The conventional antipodally symmetric Bingham matrix distribution on the Stiefel manifold is generalised. Large sample maximum likelihood estimation and uniformity tests are discussed, and a parametric model for axial orientations (X-shapes) is suggested. A generalisation of the Khatri-Mardia matrix distribution is developed to provide a model suitable for hybrids (T-shapes). Beran's results on exponential models for directional data are extended to orientation statistics to provide regression estimators and goodness-of-fit tests as alternatives to maximum likelihood estimation and likelihood ratio tests.

Keywords: Orientation statistics, Bingham matrix distribution, antipodal symmetry, exponential family.

AMS 1970 Subject classifications. Primary 62F10, secondary 62F05.

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1. Introduction

Following Downs (1972), we define an orientation statistic as a rigid m-frame in \mathbb{R}^p ($m \le p$) i.e. an $m \times p$ matrix X s.t. XX' = C, where C is an $m \times m$ symmetric positive definite matrix specifying the angles between the rows of X. Without loss of generality we suppose $C = I_m$ since all methodology for $C = I_m$ can be extended trivially for general C. We define an L-shape to be a rigid m-frame of signed directions (a conventional orientation statistic), an X-shape to be a rigid m-frame of axes, and a X-shape to be a hybrid, an m-frame of X-axes and X-shape to be a hybrid, an m-frame of X-axes and X-shapes. We assume that X-axes X-axis on the circle.

The von Mises-Fisher matrix distribution provides a suitable unimodal pdf. for orientation statistics. Naximum likelihood estimates and likelihood ratio tests have been developed by Downs (1972), Khatri and Mardia (1977) and Jupp and Mardia (1979). The conventional fully parameterised Bingham matrix distribution (Khatri and Mardia, 1977, (7.2) with $\delta = 0$) is the obvious analogue on the Stiefel manifold of Bingham's antipodally symmetric distribution on the sphere (Bingham, 1974). Maximum likelihood estimation and tests of randomness against a special case of this distribution have been treated by Jupp and Mardia (1979) and Mardia and Khatri (1977). In Section 2 we state the corresponding MLE results for the fully parameterised $2^{m'}$ -modal Bingham matrix distribution. We extend these results to a constant of the Bingham matrix distribution in Section 3, and obtain a new 'Bingham' statistic as a large sample test of uniformity against. General antipodally symmetric alternatives, a large sample approximation to the likelihood ratio statistic. In Section 4 a special case of this

distribution is suggested as a suitable model for X-shapes, and an axial Bingham statistic is obtained for a test of uniformity. The generalised Khatri-Nardia matrix distribution is used in Section 5 to provide a suitable parametric model for T-shapes, and a hybrid Rayleigh-Bingham statistic is obtained as a large sample test of uniformity. Beran's results on rotationally invariant exponential models for directional data are extended to the Stiefel manifold in Section 6, to provide regression estimators and goodness of fit tests within the generalised Khatri-Nardia family of distributions, as alternatives to the computationally inconvenient maxisum likelihood estimators and likelihood ratio tests.

2. The Binghes matrix distribution

If X is an amp matrix random variable $(n \le p)$ with pdf $(2\pi)^{-\frac{1}{2mp}} |X|^{\frac{1}{2m}} |V|^{\frac{1}{2m}} = \exp(-\frac{1}{2}K(X-\mu)V(X-\mu)^{\frac{1}{2}}) dX$ (2.1)

where K is are symmetric positive definite, and V is pup symmetric positive definite, then if $\mu=Q_{mp}$, an amp matrix of zeros, the pdf of X, conditional on XX'=I_m is (Khatri and Mardia, 1977, (7.2))

$$etr(-\gamma m^{-1} I_m - igxvx') [dx]$$
 (2.2)

where [dX] denotes the uniform distribution on the Stiefel manifold O(m,p), and $\gamma=\gamma(X\oplus V)$ is a normalising constant which depends only upon the diagonal matrices D_{K} , D_{V} of eigenvalues of K and V. Series expansions for $e^{+\gamma}$, a hypergeometric function of two matrix arguments, have been given by Srivastava and Carter (1980). For reasons which will become apparent, we denote the distribution (2.2) $B(X,m,p,K\oplus V)$. Its parameter space has dimension $(\frac{m+1}{2})+(\frac{p+1}{2})-2$ when $1\leq m\leq p-1$, since $B(X,m,p,(\alpha K)\oplus (\alpha^{-1}V+\beta I_{p}))=B(X,m,p,K\oplus V)$ for all real scalars $\alpha\neq 0$, β (cf. Singham, 1974, Lemma 2.1). Similarly, when m=p $B(X,p,p,(\alpha K+\beta_1 I_p)\oplus (\alpha^{-1}V+\beta_2 I_p))=B(X,p,p,K\oplus V)$, where without loss of

generality we may assume trace (K-V) = 0, so that the parameter space has dimension $2\binom{p+1}{2} - 3$. Where convenient to identify parameters uniquely we shall assume that $\Psi_{p_2} = 0$ (and $k_{pp} = 0$ if m = p), or, if dealing in spectral decompositions, that the entries in $-D_K$ and D_V are in decreasing order with $(L_V)_{pp} = 0$ (and $(D_K)_{11} = 0$ if m = p). We assume that the elements of D_K and D_V are distinct so that K has a unique matrix $Q \in O(m^1, m)$ of eigenvectors and V has a corresponding matrix $M \in O(p-1, p)$. From Theobald (1975, Theorem 1), the distribution (2.2) has 2^{m^1} modes at the points $X = Q^1M_1$, where M_1 is the $m^1 \times p$ matrix of the first $m^1 = \min(m, p-1)$ columns of M. The multiplicity 2^{m^1} arises from the possible sign changes of the columns of Q and M_1 . I am grateful to Dr Theobald for first drawing my attention to this.

A random sample x_1, x_2, \ldots, x_n on O(m,p) from the distribution (2.2) has log likelihood

where $Y=n^{-1}\sum\limits_{j=1}^{n}X_{j}\otimes X_{j}^{i}=(y_{jk,lq})$, $1\leq j,q\leq n$, $1\leq k,l\leq p$. The distinct elements of Y, excluding those for which (k,l)=(p,p) (and also those for which (j,q)=(p,p) when m=p) are sufficient but not minimally sufficient unless m=1 (the case of directional data), because $v(m,p)=(\frac{mp+1}{2})-(\frac{m+1}{2})\geq (\frac{m+1}{2})+(\frac{p+1}{2})-2$, with equality only when m=1, and $v(p,p)=(\frac{p^2+1}{2})-2(\frac{p+1}{2})+1>2(\frac{p+1}{2})-3$. The following is a consequence of Berk (1972), and elementary calculus.

Theorem 2.1

(a) For sufficiently large n, there exist unique MLRs \hat{X}, \hat{V} subject to the condition $\hat{V}_{pp} = 0$ (and $\hat{K}_{pp} = 0$ and trace $(\hat{X} - \hat{V}) = 0$ when n = p) of the parameters in $B(X,n,p,X \in V)$. The MLRs are the solutions of

$$\left(\frac{\partial \gamma}{\partial K}\right)_{(K,V) = (\hat{X},\hat{V})} = -\frac{1}{2} H_1(\hat{V})$$

and

$$\begin{pmatrix} \frac{2\gamma}{2} \end{pmatrix}_{(K,V) = (\hat{K}, \hat{V})} = -\frac{1}{2} W_2(\hat{K})$$

where $W_1(V) = n^{-1} \sum_{i=1}^{n} X_i V X_i^i$ and $W_2(X) = n^{-1} \sum_{i=1}^{n} X_i^i K X_i^i$.

(b) (Spectral version) If $K=Q'D_{K}Q$ and $V=M'D_{V}H$ are unique spectral decompositions of K and V, where $Q \in O(n^{\epsilon},m)$, $N \in O(p-1,p)$ and D_{K} , D_{V} are respectively $m' \times m'$ and $(p-1) \times (p-1)$ diagonal matrices (and trace $(D_{K}-D_{V})=0$ if m=p), then for sufficiently large n with probability 1 there exist unique MIEs \hat{Q} , \hat{R} , \hat{D}_{K} , \hat{D}_{V} of Q, N, D_{K} , D_{V} given by the unique spectral decompositions

 $\mathbf{W}_{1}(\hat{\mathbf{v}}) = \hat{\Omega}^{*} \hat{\mathbf{D}}_{\mathbf{W}_{1}} \hat{\mathbf{Q}}, \ \mathbf{W}_{2}(\hat{\mathbf{R}}) = \hat{\mathbf{R}}^{*} \hat{\mathbf{D}}_{\mathbf{W}_{2}} \hat{\mathbf{R}} \quad \text{and the equations}$ $\left(\frac{\partial \mathbf{v}}{\partial \mathbf{D}_{\mathbf{X}}}\right)_{(\mathbf{D}_{\mathbf{X}}, \mathbf{D}_{\mathbf{V}})} = (\hat{\mathbf{D}}_{\mathbf{X}}, \hat{\mathbf{D}}_{\mathbf{V}}) \quad = -\mathbf{i}_{1} \hat{\mathbf{D}}_{\mathbf{W}_{1}}$

$$\left(\frac{\partial v}{\partial \hat{D}_{\psi}}\right)_{(\hat{D}_{\chi},\hat{D}_{\psi}) = (\hat{D}_{\chi},\hat{D}_{\psi})} = \rightarrow_{i} \hat{D}_{M_{2}}.$$

We offer no algorithm for the evaluation of \hat{R} and \hat{V} . Given suitable initial approximations \hat{R}_0 , \hat{V}_0 it should be possible to construct an iterative procedure, given tractable series expansions for γ and its first derivatives (see Bingham, 1976), but considerable computational effort is necessary.

Jupp and Mardia (1979, Theorems 1(b) and 4) have obtained the analogue of Theorem 2.1 for the special case $B(X,m,p,I_m \oplus V)$ which has parameter space of dimension $\frac{1}{2}(p-1)(p+2)$ provided m < p. We note that $B(X,p,p,I_p \oplus V)$ is the uniform distribution so their results are invalid for square orientations. The log likelihood of a sample from

 $B(x,x,p,I_x \oplus V)$, x < p,

is $-n \gamma (I_m \oplus V) - \frac{1}{2}n$ trace VY^* (2.4) where $Y^* = n^{-1} \sum_{i=1}^{n} X_i^* X_i$ is pxp symmetric, positive definite with probability 1. The distinct elements of Y^* , excluding y_{pp}^* say, are minimally sufficient for V, subject to $v_{pp} = 0$ say. A simple large sample test of uniformity against alternatives (2.4), asymptotically equivalent to the likelihood ratio statistic, may be obtained by generalising Bingham's Theorem 5.2 (1974, p.1208). We obtain

Theorem 2.2

On the null hypothesis of uniformity the statistic . $S_{11} = (\text{trace}(Y^{+2}) - \pi^2/p) \ np(p-1) (p+2)/2\pi(p-m) \ \text{is asymptotically distributed}$ as χ^2 on $\nu(1,p) = \frac{1}{2}(p-1) (p+2)$ degrees of freedom.

Proof (A simpler version of Theorem 3.2 below).

If χ^* is the $\binom{p+1}{2}$ -vector of the distinct elements of Y^* , then Z^* , the asymptotic variance matrix (Mardia and Khatri, 1977 p.469) of $n^3\chi^*$ has rank v(1,p) and a generalised inverse [p(p-1)(p+2)/2m(p-m)] blockdiag $(I_p, 2I_{\binom{p}{2}})$. Since Y^* has null expectation $xp^{-1}I_p$, the result follows immediately (see also Khatri and Mardia, 1977, p.471, for an alternative derivation).

Remarks 1. S, is undefined when m=p

2. $B(X,n,p,X \oplus I_p)$, the other obvious special case of (2.2), is the uniform distribution for all n, $1 \le n \le p$.

3. A generalisation

$$etr(-\gamma (mp)^{-1} I_{mp} - \frac{1}{2} AX \in X') [dX]$$
 (3.2)

obtained when $XX' = I_m$ and $y = Q_{ap}$. Here A is mpxmp symmetric positive definite with distinct eigenvalues $a_1 > \dots > a_{ap}$, and $\gamma = \gamma(A)$ is a normalising constant. The distribution (3.2), denoted B(X,m,p,A) is antipodally symmetric and has parameter space of dimension v(m,p), since $B(X,m,p,A) = B(X,m,p,A+A_1 \oplus I_p)$ for all real man symmetric matrices a_1 , and $B(X,p,p,A) = B(X,p,p,A+A_1 \oplus I_p + I_p \oplus A_2)$ for all real pxp symmetric matrices a_1 , a_2 , where without loss of generality we may assume trace $(a_1 - a_2) = 0$. Where convenient to identify parameters uniquely we shall assume that $a = (a_{jk,fq})$ $1 \le j$, $q \le m$, $1 \le k, k \le p$, satisfies the conditions

$$a_{jp,pq}=0$$
 for all j,q, and, if $m=p$, $a_{pk,lp}=0$ for all k,£. (3.3)

A random sample from the distribution (3.2) has log likelihood

$$-n\gamma(\lambda) - \ln trace \lambda Y$$
 (3.4)

with $Y = (y_{jk}, lq)$ as in (2.3). The distinct elements of Y, excluding those corresponding to (3.3), are minimally sufficient for λ . From Berk (1972), and differentiation we obtain.

Theorem 3.1

For sufficiently large $\,n$, with probability 1 there exists a unique MLE \hat{A} of A subject to (3.3), which is the solution of

$$\left(\frac{\partial \gamma}{\partial \lambda}\right)_{(A=\hat{A})} = -i\gamma .$$

As with theorem 2.1, there are considerable computational difficulties associated with the search for \hat{A} . In particular, no emplicit form of $\gamma(A)$ is currently available.

A Bingham statistic for testing uniformity against all antipodally symmetric alternatives of the form $B(X,m,p,\lambda)$ may be obtained as follows.

Theorem 3.2

Let $z_1 = y - p^{-1}$ I and $z_2 = (z_{jk,lq}^{(2)}) = \frac{1}{2}(y_{jk,lq} - y_{qk,lj})$. On the null hypothesis of uniformity the statistic $B_{mp} = n(p-1)[\frac{1}{2}(p+2) \text{ trace } (z_1^2z_1) - \text{ trace } (z_2^2z_2)] \text{ is asymptotically distributed as } \chi^2 \text{ on } \nu(m,p) \text{ degrees of freedom.}$

Proof

On the null hypothesis Y has expectation p^{-1} I Consider first the case m<p. The $(\frac{mp+1}{2})$ distinct elements of Y may be written as a vector

 $y = (\langle y_{11} \rangle, \dots, \langle y_{mn} \rangle, \langle y_{12} \rangle, \dots, \langle y_{m-1,m} \rangle)^{*}$ where each $\langle y_{jj} \rangle, 1 \le j \le m$, is a $\binom{p+1}{2}$ -vector

 $(y_{j1,1j}, y_{j2,2j}, ..., y_{jj,jj}^{-p^{-1}}, ..., y_{jp,pj}, y_{j1,2j}, y_{j1,3j}, ..., y_{jp-1,pj})$ and each $\langle y_{jk} \rangle$, $1 \le j < k \le m$, is a p^2 -vector

 $(y_{j1,1}, \dots, y_{jp,pl}, y_{j1,2}, y_{j2,1}, \dots, y_{jp-1,pl}, y_{jp,p-1})^{1}$. Using Anderson and Stephens (1972, p.616) it follows that $n^{4}y$ has covariance matrix $\mathbf{I} = [(p-1)(p+2]^{-1}$ blockdiag($(2C_{mp} \oplus blockdiag(C_{pp}, 2I_{pp}))$),

 $I_{m} = b \operatorname{lockdiag}(C_{pp}, p^{-1} \ I_{pp} = D))$ where $C_{mp} = I_{m} - p^{-1} \ I_{mn}$, I_{mn} is an man matrix of ones, and $D = \begin{bmatrix} p+1, & -1 \\ -1, & p+1 \end{bmatrix}$.

Since $C_{mp}^{-1} = C_{m,m-p}$ and $C_{pp}^{-1} = I_{p}$ is a generalised inverse of C_{pp} , it follows that

 $I = blockdiag((\frac{1}{2}(p-1)(p+2)C_{m,m-p}) = blockdiag(I_p,2I_p)),$

 $t_p \in blockdiag((p-1)(p+2)) t_p, t_p \in b_1)$

is a generalised inverse of Γ , where $D_1 = \begin{bmatrix} (p^2-1), (p-1) \\ (p-1), (p^2-1) \end{bmatrix}$. As Γ has rank v(m,p) and the quadratic form $n \ge \Gamma$ reduces to B_{mp} as above, it follows that B_{mp} is asymptotically distributed as χ^2 on v(m,p) degrees of freedom.

The only change necessary when n=p is that $C_{m,n-p}$ should be replaced by $I_p (= C_{pp}^-)$. We obtain B_{pp} as above, where now Σ has rank v(p,p).

Remarks 1. When $p \ge 4$, B_{pp} is precisely the 'Bingham' statistic obtained by Prentice (1981, (3.4)) from consideration of the (0,2)-th and (0,1,1)-th characters of the irreducible continuous representations of the rotation group $O^+(p)$.

2. When m=1, B_{lp} is the conventional Bingham statistic for directional data, since then $Z_2 = Q_{pp}$ and Z_1 is symmetric.

4. Axial orientation statistics

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The distribution (3.2) (or (2.2)) may be specialised to give a parametric model suitable for X-shapes. We require a probability density on O(m,p) invariant under sign changes of any row of the random variable X. This is achieved if A satisfies the conditions $a_{jkj,q}=0$ if $j\neq q$. We write $B^{(ax)}(X,m,p,E)$ for the density

$$etr(-\gamma p^{-1} i_p - i_2 i_{j=1}^m i_{j=j-1}^m)$$
 (4.1)

where $\gamma = \gamma(E)$ is a normalising constant, E is an arpsp array with jth layer E_j , $1 \le j \le n$, $e_{jkk} = e_{jk,k,j}$, $1 \le k,k \le p$, and E_j is the j-th row of the random variable X. Since $B^{(ax)}(X,n,p,E) = B^{(ax)}(X,n,p,E+E^*)$ for all real arrays with elements $e_{jkk}^* = e_j$, dependent on layer only, it follows that the distribution (4.1) has parameter space of dimension $\eta(n,p) = n \binom{p+1}{2} - n = \frac{1}{2} \pi(p-1) (p+2)$, when n < p. If n = p, e_{jkk}^* may be of the more general form $e_j + f_{kk}$ where $F = (f_{kk})$ is p = p symmetric, and without loss of generality, $f_{pp} = 0$. Bence for square axial orientations the parameter space of the distribution (4.1) has dimension $\eta(p,p) = p \binom{p+1}{2} - \binom{p+1}{2} - p + 1 = \frac{1}{2}(p-1)^2(p+2) = \eta(p-1,p)$. Where convenient to identify parameters uniquely, we shall assume that

$$e_{jpp} = 0$$
 for all j, $1 \le j \le m$, and if $m = p$, $E_p = 0$ also. (4.2)

A random sample from the distribution (4.1) has log likelihood

$$-n\gamma(E) \xrightarrow{-1}_{2} n \text{ trace } \sum_{j=1}^{m} \sum_{j=1}^{2} Y_{j}$$
 (4.3)

where $Y_j = n^{-1} \sum_{i=1}^{n} \underline{x}_j^{(i)} \underline{x}_j^{(i)}$, $\underline{x}_j^{(i)}$ representing the jth row of X_i .

The distinct elements of Y_1, \ldots, Y_m , excluding those corresponding to (4.2), are minimally sufficient for E. As in Section 3 we obtain

Theorem 4.1

For sufficiently large $\,n$, with probability 1 there exists a unique MLE \hat{E} of E , subject to (4.2), which is the solution of

$$\left(\frac{\partial Y}{\partial E}\right)_{(E=\hat{E})} = -\frac{1}{2}(Y_1, \ldots, Y_m).$$

An axial Bingham statistic, suitable for testing uniformity against alternatives (4.1) may be obtained from a simplified version of Theorem 3.2. From consideration of the asymptotic null distribution of the first $m(\frac{p+1}{2})$ elements of $n^{\frac{1}{2}}y$ we obtain

Theorem 4.2

On the null hypothesis of uniformity the statistic $B_{mp}^{(ax)} = {}^{1}m(p-1)(p+2) \text{ (trace } (\sum_{j=1}^{n} Y_{j}^{2}) - n/p) \text{ is asymptotically distributed}$ as χ^{2} on $\eta(n,p)$ degrees of freedom.

Remark S_u (Theorem 2.2) = $\frac{1}{2}$ mp(p-1)(p+2) (trace(($\sum_{j=1}^{\infty} Y_j$)²) - $\frac{1}{2}$ p)/m(p-m), provided m < p.

5. Hybrids

A parametric model suitable for T-shapes may be obtained from the generalised Khatri-Mardia distribution

$$etr(-\gamma(mp)^{-1} I_{mp} - \lambda X \bullet X' + \lambda y \bullet X') , \qquad (5.1)$$

from (3,1), conditional on XX' = I_m , when $\mu \neq O_{mp}$. We require that the pdf should be invariant under sign changes of any of the first m_1 , rows (the axes) of X. This can be achieved by requiring that $\mu = \begin{pmatrix} O_{m,p} \\ \mu_2 \end{pmatrix}, \text{ where } \mu_2 \text{ is an } m_2 \times p \text{ matrix of means, } O < m_2 = m - m_1 < m \text{ ,}$ and that A satisfies the condition $a_{jk,\ell q} = 0$ if $j \neq q$ and $\min(j,q) \leq m_1 \text{ We write } B^{(hy)} \text{ } (X,m_1,m_2,p,\mu_2,E,A_2) \text{ for the density }$ $\exp(-\gamma - \frac{1}{2} \operatorname{trace}(\sum E_j \times j \times j) + \operatorname{trace}(A_2 \mu_2 \otimes X_{(2)}' - \frac{1}{2} A_2 X_{(2)} \otimes X_{(2)}')) \tag{5.2}$

where $\gamma = \gamma(E_1A_2)$ is a normalising constant, E is as in Section 4, but with only m_1 layers, A_2 is the $m_2p_1m_2p$ submatrix of A corresponding to $X_{(2)}$, the last m_2 rows of the random variable X. Since $B^{(hy)}(X_1m_1,m_2,p,\mu_2,E_1A_2) = B^{(hy)}(X_1m_1,m_2,p,\mu_2,E+E^*,A_2+A_2^* \oplus I_p)$

for all real E* as in Section 4 (but with only m_1 layers), and all real symmetric $m_2 \times m_2$ matrices h_2^+ , it follows that when $m = m_1 + m_2 < p$, the distribution (5.2) has parameter space of dimension $\phi(m_1, m_2, p) = m_1 \binom{p+1}{2} + \binom{m_2p+1}{2} - m_1 - \binom{m_2+1}{2} + m_2p = \eta(m_1, p) + \nu(m_2, p) + m_2p$.

When m=p, the more general result

 $\mathbf{B}^{(\mathrm{hy})} \quad (\mathbf{X}, \mathbf{m}_1, \mathbf{m}_2, p, \boldsymbol{\mu}_2, \mathbf{E}, \boldsymbol{\lambda}_2) = \mathbf{B}^{(\mathrm{hy})} \quad (\mathbf{X}, \mathbf{m}_1, \mathbf{m}_2, p, \boldsymbol{\mu}_2, \mathbf{E} + \mathbf{E}^*, \boldsymbol{\lambda}_2 + (\boldsymbol{\lambda}_2^* \bullet \mathbf{I}_p) + (\mathbf{I}_{\mathbf{m}_2}^* \bullet \mathbf{F}))$ obtains, where F and E* are of the more general form in Section 4, and so, the distribution (5.2) has parameter space of dimension $\phi(\mathbf{m}_1^*, \mathbf{m}_2, p) = \eta(\mathbf{m}_1^*, p) + \nu(\mathbf{m}_2, p) + \mathbf{m}_2 p \text{ , where } \mathbf{m}_1^* = \min(\mathbf{m}_1, p - \mathbf{m}_2 - 1).$ Where convenient to identify parameters, we shall assume that $\boldsymbol{\lambda}_2$ satisfies (3.3), and that

 $e_{jpp} = 0$ for all $j, 1 \le j \le m_1$, and if $m_1 + m_2 = p$, $m_{m_1} = 0$ (5.3)

A random sample from the distribution (5.2) has log likelihood

$$-n\gamma (E_{i}A_{2}) - \frac{1}{2}n \text{ trace} (\sum_{j=1}^{n} E_{j}Y_{j}) + n \text{ trace} (A_{2}\mu_{2} \bullet \bar{X}'_{(2)} - \frac{1}{2} A_{2}Y_{(2)})$$
 (5.4)

where $\bar{x}_{(2)}$ is the $m_2 \times p$ matrix of means of the last m_2 rows of the data matrices x_1, \ldots, x_n , and $y_{(2)}$ is the $m_2 p \times m_2 p$ submatrix of $y_{(2)}$ corresponding to the last m_2 rows. The distinct elements of $\bar{x}_{(2)}, y_1, \ldots, y_{m_1}, y_{(2)}$, excluding those corresponding to (3.3) and (5.3), are minimally sufficient for y_2 , y_2 and y_3 .

Theorem 5.1

For sufficiently large n, with probability 1 there exists a MLE $\hat{\theta} = (\hat{\mu}_2, \hat{A}_2, \hat{E})$ of $\theta = (\mu_2, A_2, E)$, subject to (3.3) and (5.3), which is the solution of

$$\left(\frac{\partial \gamma}{\partial \mu_{2,j}t}\right)_{(\theta=\hat{\theta})} = \sum_{kq} a_{jk,tq} \bar{x}_{2,qk}$$

$$\left(\frac{\partial \gamma}{\partial E}\right)_{(\theta=\hat{\theta})} = -\frac{1}{2} (Y_1, \dots, Y_{m_1^1})$$

$$\left(\frac{\partial \gamma}{\partial A_2}\right)_{(\theta=\hat{\theta})} = \underline{\mu}_2 \bullet \bar{x}'_{(2)} - \frac{1}{2} Y_{(2)} .$$

A large sample test of uniformity of T-shapes against alternatives (5.2) may be obtained by slight modification of Theorems (3.2) and (4.2). We obtain a hybrid Rayleigh-Bingham statistic:-

Theorem 5.2

On the null hypothesis of uniformity, the statistic

 $B_{m_2P}^{(hy)} = B_{m_2P}^{(ax)} + B_{m_2P}^{(ax)} + pn$ trace $\tilde{\chi}_{2\tilde{\chi}_2^0}^{(x)}$, with $B_{m_1P}^{(ax)}$ as in Theorem 4.2, and $B_{m_2P}^{(x)}$ as in Theorem 3.2, is asymptotically distributed as χ^2 on $\phi(m_1^2, m_2, p)$ degrees of freedom.

Proof

 X_2 has expectation Q_{m_2P} and is asymptotically uncorrelated with Y_1, \ldots, Y_{m_1} and $Y_{(2)}$. Using the method of Theorem 3.2 we obtain a quadratic form in $m_2p+(\frac{p+1}{2})+m_1(\frac{p+1}{2})$ variables with covariance matrix of rank $\phi(m_1^*,m_2,p)$, which reduces to $B_{m_1m_2p}^{(hy)}$ as stated.

6. Exponential models and regression estimators

It is instructive to consider these matrix Bingham and Khatri-Nardia distributions within the context of the rotationally invariant exponential family of distributions for orientation statistics, obtained by generalising Beran's (1979) exponential family for directional data. Provided good multivariate density estimates are available, the obvious analogues of Beran's regression estimators ((1.10) ibid.) and goodness of fit tests (Section 5, ibid.) should be considerably more convenient computationally than exact PLEs and likelihood ratio tests.

Consider first the case m=p, and the general exponential model $\exp(h(X)-\gamma(h))$, $h\in B$, where H is associated with the g g, where H is associated with the g g-th character of the irreducible continuous representations of $0^+(p)$, as in Prentice (1981). The von Mises-Fisher matrix distribution spans $H_{0,1}$, of dimension p^2 , and has basis $\beta_1=\{x_{ij},\ 1\leq i,j\leq p\}$. The generalised Bingham matrix distribution (3.2) spans $H_2=H_{0,2}\oplus H_{0,1,1}$ of dimension v(p,p) when $p\geq 4$, and spans $H_2\oplus H_1$ when p=3. A basis is provided by $\beta_2=\{x_{ij}x_{kl},\ 1\leq i\leq k\leq p,\ 1\leq j\leq l\leq p,\ \exp(\operatorname{auding}\operatorname{cases}\operatorname{corresponding}\operatorname{to}\ (3.3)\}$. When $m\leq p$, corresponding results are obtained by excluding the last (p-m) rows of X. We obtain H_2 of dimension v(m,p) with basis

 $\{x_{i,j}x_{k,l}, 1 \le i \le k \le m, 1 \le j \le l \le p, \text{ excluding cases } (3,3)\}$.

For X-shapes, and the distribution (4.2) we proceed similarly. We obtain $\{x_{i,j}x_{i,k}, 1 \le i \le m', 1 \le j \le k \le p\}$, excluding cases corresponding to (4.2)}, of dimension $\eta(m',p)$. For hybrids, and the distribution (5.2), a basis is $\{x_{i,j}, m_1 < i \le m, 1 \le j \le p\}$ \emptyset $\{x_{i,j}x_{i,k}, 1 \le i \le m'_1, 1 \le j \le k \le p\}$ excluding cases corresponding to (5.3)} \emptyset $\{x_{i,j}x_{k,l}, m_1 < i \le k \le m, 1 \le j \le l \le p\}$, excluding cases corresponding to (3.3)}, of dimension $\emptyset(m'_1, m_2, p)$.

Since Beran's results (1979) apply to the canonical exponential family of any compact space, his formulae (1.10) for estimators, (5.5) for approximate tests, and their extensions to interval estimation, may be used in large samples on orientation statistics of all types, provided only that suitable robust multivariate density estimates are available.

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